



Tools for developing cost-effective decisions for managing invasive pest eradications



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Partners/Collaborators

- Collaborators
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- Partners
 - Department of Jobs Precincts and Regions, Victoria
 - CSIRO
 - Adelaide University
 - Landcare Research New Zealand

Objectives

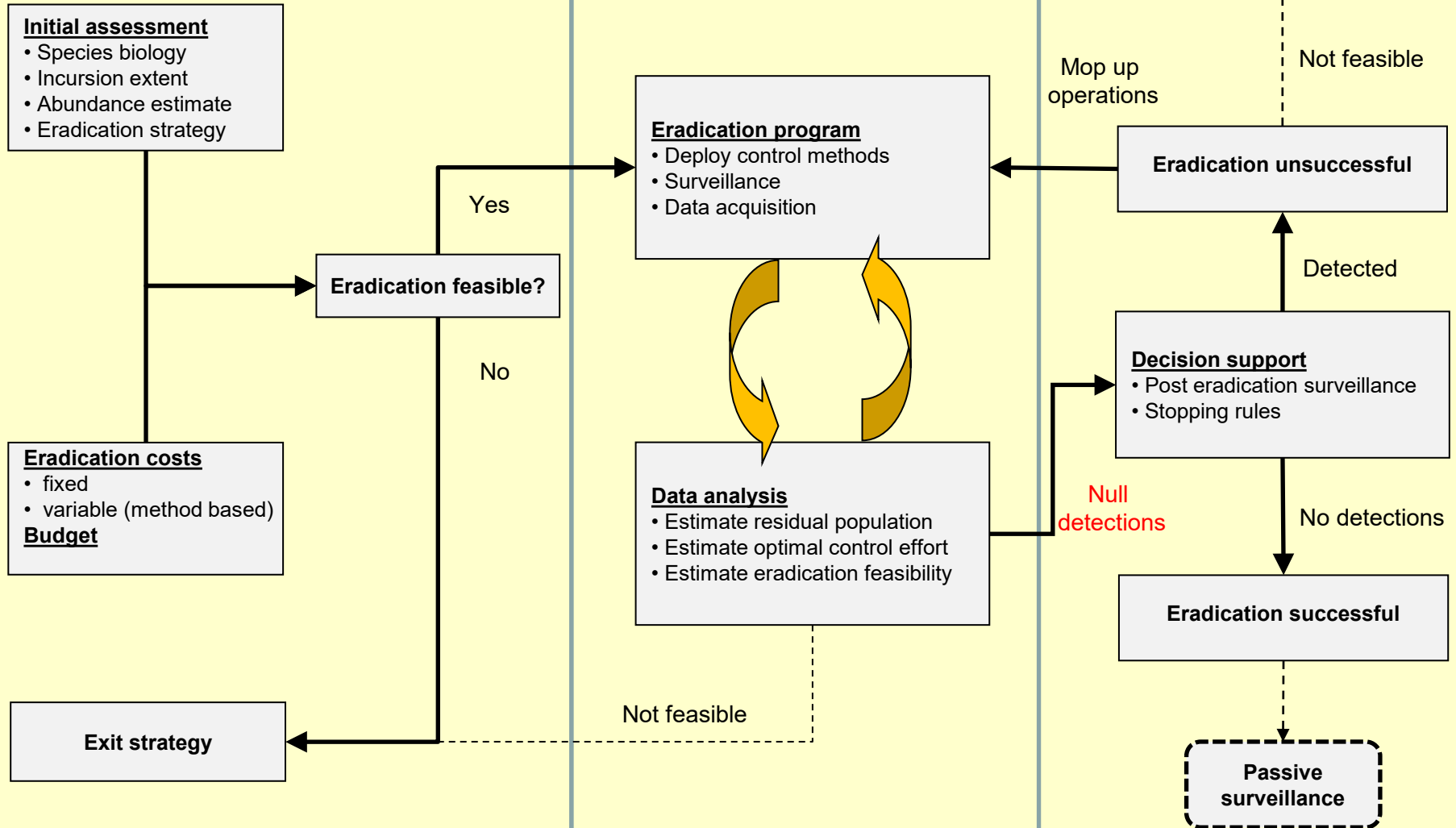
- Develop new tools/systems for guiding decisions around an eradication response for invasive pests.
- Improve capability of agencies to make cost-effective decisions around pest eradications by:-
 1. developing a flexible suite of decision support tools using data from active eradication case studies
 2. developing a bioeconomic framework for conducting pest eradication programs
 3. packaging the decision tools and bioeconomic framework into a user-friendly software package that is easily accessible to managers.

Eradication Response Framework

Assessment phase

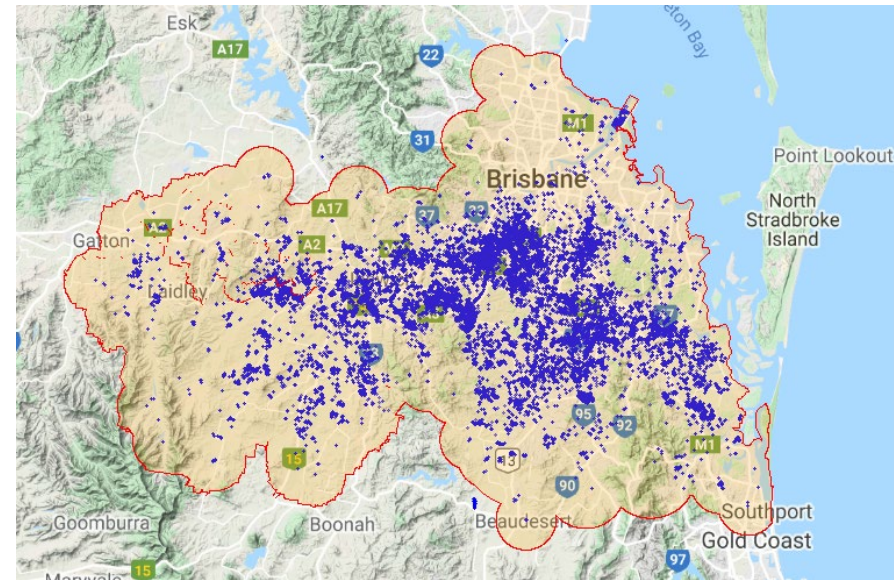
Eradication phase

Evaluation phase



Initial Assessment Phase

- Objectives
 - Obtain baseline information about the incursion
 - Extent (spatial distribution)
 - Abundance/Occupancy (habitat/risk relationships)
 - Initial eradication feasibility assessment
 - Can pest be eradicated using chosen method(s)?
 - Estimate cost to achieve eradication



Initial Assessment Phase

- Initial pest abundance and extent
 - Collection of monitoring data
 - Establish sampling frame (region extent, risk layer, sampling units)
 - Monitoring design (detection device layout)
 - Deploy
 - Collate data
- ➡ Eradication tools

Pre-implementation Monitoring

Select a model to use: ☐ Occupancy ☒ Royle-Nichols ☐ N-mixture ☐ REST

Region boundary (.shp)
Browse... 4 files
Upload complete

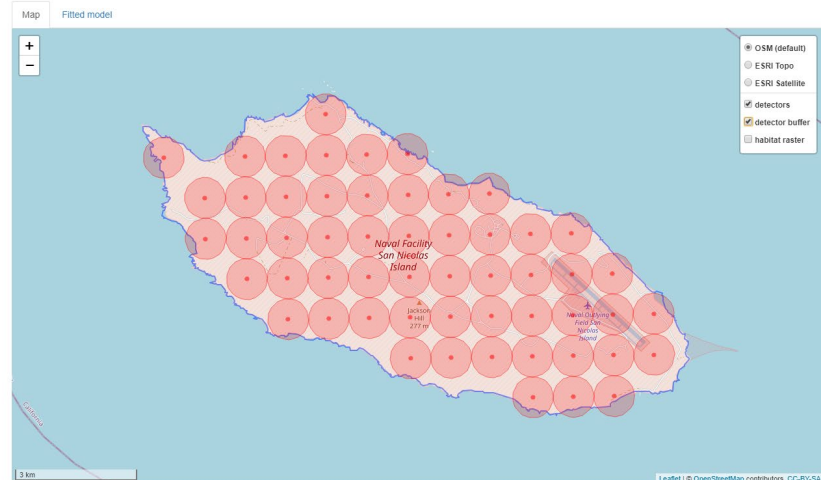
Habitat raster (.tif, .asc)
Browse... No file selected

Detector locations (.csv)
Browse... No file selected

Detection histories or counts (.csv)
Browse... No file selected

Plot map
Raster sampling radius: 500
Raster transparency: 0.2

Fit model
Estimate Density Surface
Download Density Raster



Initial Assessment Phase

- Initial abundance estimates – software backend
 - Models
 - N-mixture models – replicate counts of individuals per device/unit
 - Royal-Nichols model – presence/absence data per device/unit
 - Occupancy model – presence/absence data
 - REST model – Time to first detection/staying time (camera data)
 - All models fit by maximum likelihood using custom built R package
 - “eradicate” (<https://github.com/eradicate-dev/eradicate>)

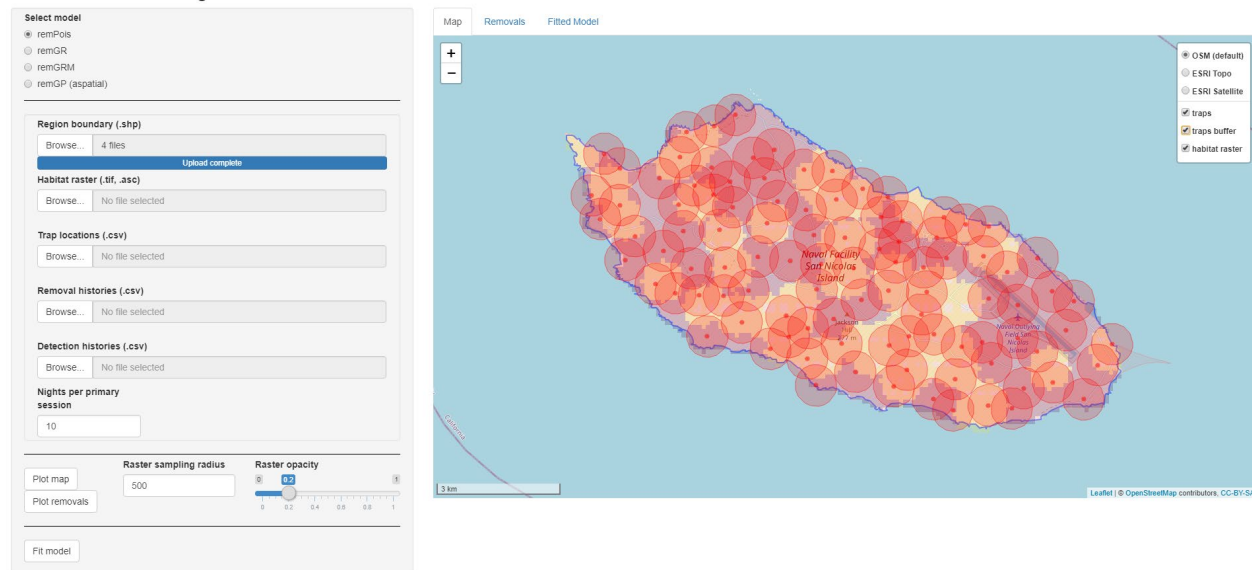
Initial Assessment Phase

- Eradication feasibility Tool (Under Development)
 - Assess the feasibility of eradicating the pest incursion
 - Inputs:
 - Initial abundance estimate/spatial distribution
 - Baseline pest removal design - methods/device(s)
 - Unit costs
 - Based on inputs conduct a search for the optimal design that results in eradication for a fixed cost.
 - Alternatively, estimate the likely cost to achieve eradication for the given inputs.

Eradication Phase

- Objectives – track progress towards nominal eradication
 - Collection of monitoring data
 - Deploy selected pest removal strategy
 - Collect data at periodic intervals
 - Collate data
 - Update progress  Eradication tools
 - Residual population size estimate
 - Residual spatial distribution

Eradication Monitoring



Evaluation phase

- 'Proof of freedom'
- Following completion of eradication phase
- Declaration of nominal pest 'freedom'
 - Assessment of the amount of additional surveillance required to declare eradication success
 - Stopping rules
 - Minimise Type I error (probability of an incorrect declaration)
 - Minimise costs of Type I and II errors (tradeoff surveillance costs with costs of making an incorrect declaration)

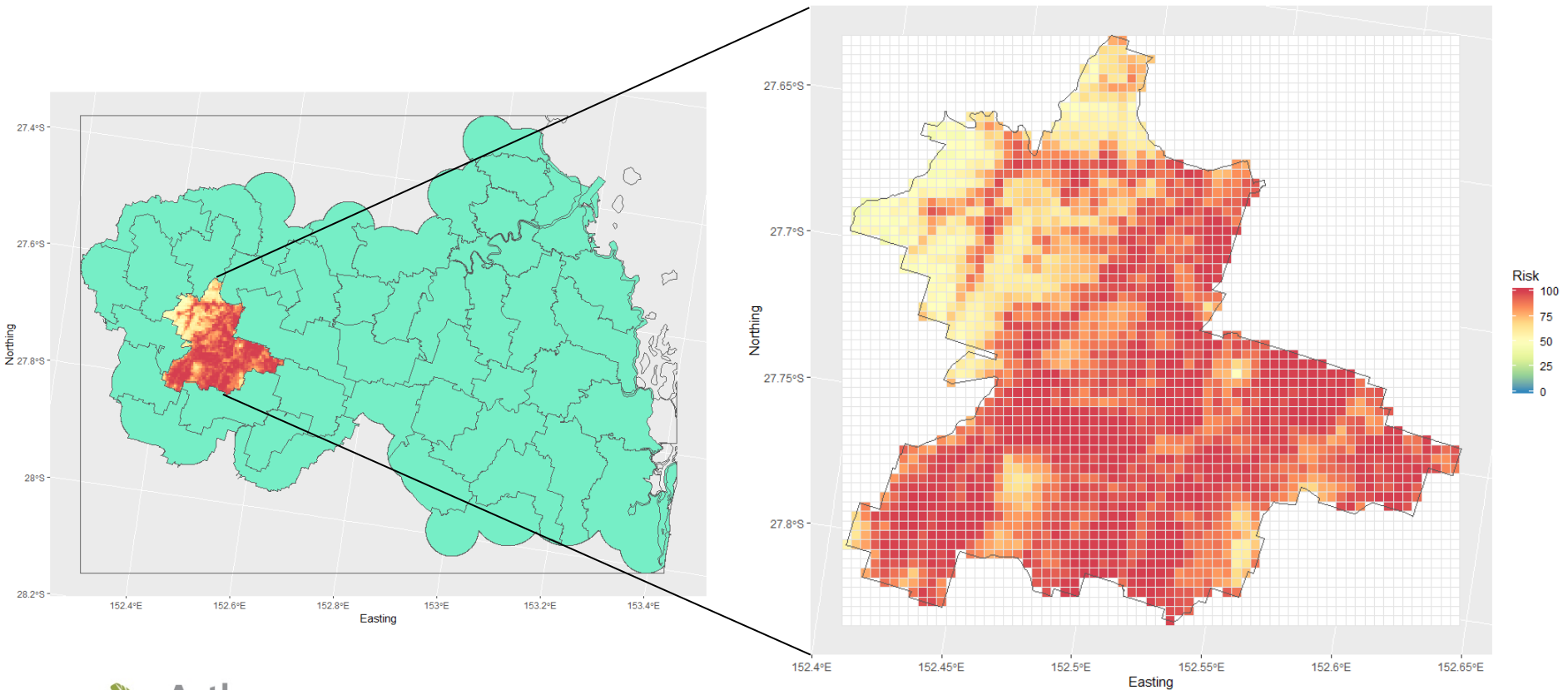


Spatial surveillance

Surveillance Units (360 x 360 m)

Management Units

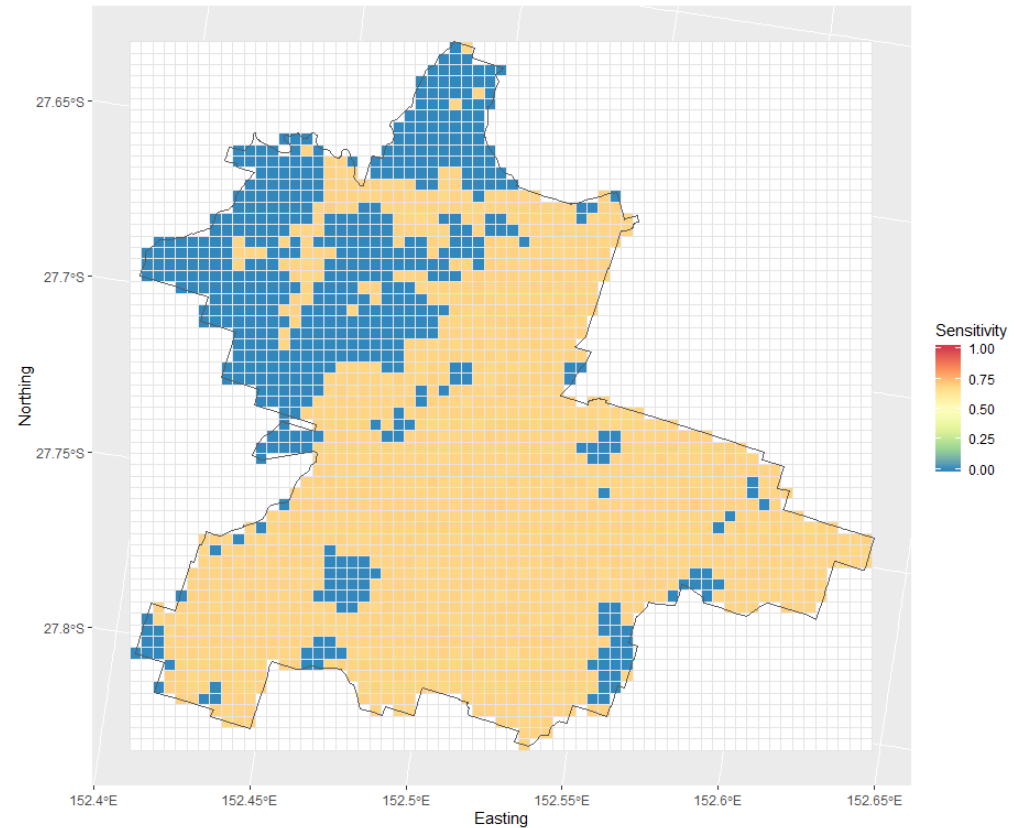
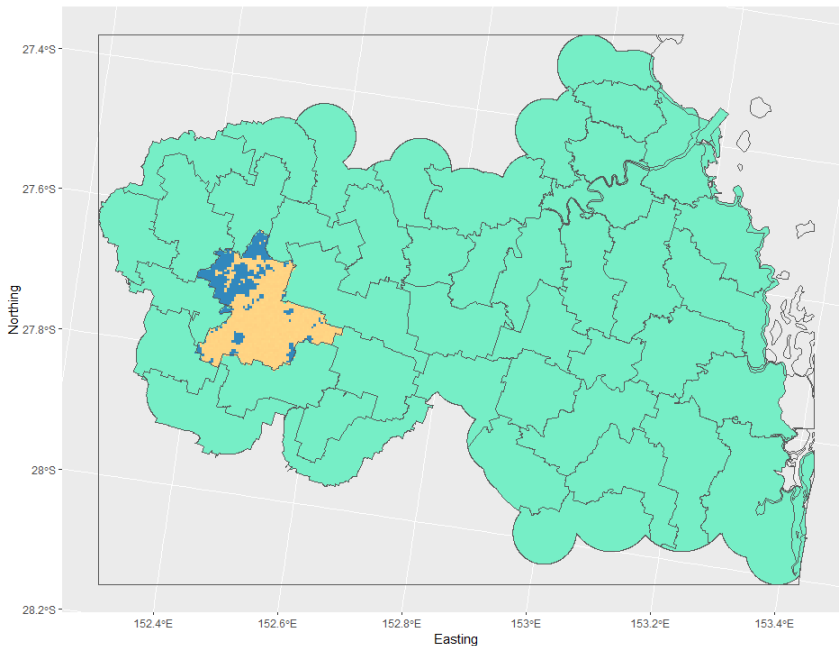
Habitat suitability



Surveillance sensitivity - SSe

- Assess surveillance sensitivity (SSe) allowing for incomplete coverage

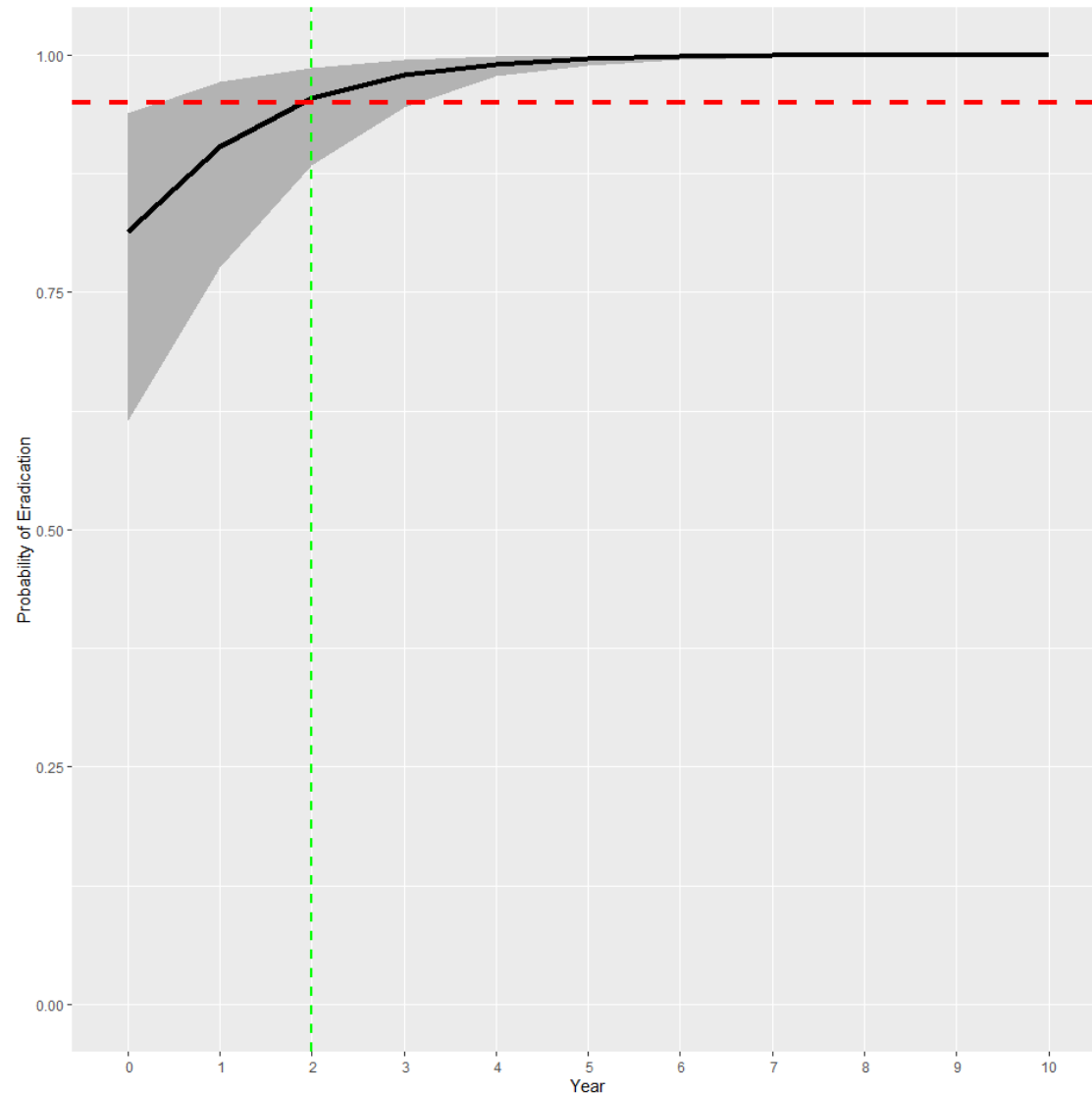
18,000 ha: SSe = 0.55



Stage 1: Declaration of freedom in MU

Prior estimate = 0.8 (0.61, 0.92)

Freedom declaration after two
years of surveillance
(Type I error = 0.05)



Proof-of-absence module

POA tool example – Stoat eradication in Greater Wellington

Run model Advanced inputs Troubleshooting

Shiny proof-of-absence interface

Select example set

CK stoats

Minimum relative risk value

1

epsg

2193

Show 10 entries

Search:

	Mean g0	Stdev g0	Mean sigma	Stdev sigma
A24	0.1	0.01	90	10
DOC200	0.1	0.01	90	10
DOC250	0.1	0.01	90	10
VICTOR	0.1	0.01	90	10

Showing 1 to 4 of 4 entries

Previous

1

Next

Run params script

Run inputs

Prior min

0.2

Prior mode

0.4

Prior max

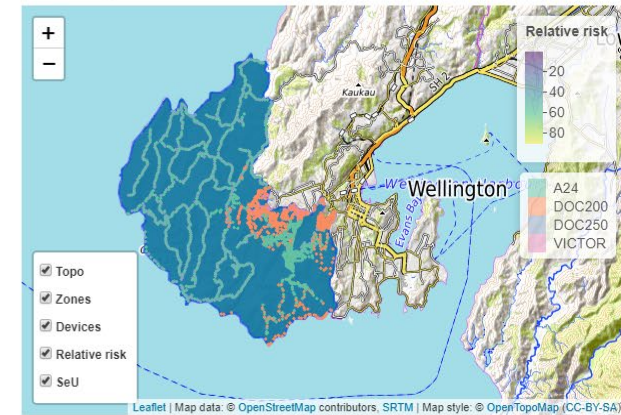
0.85

sigmean

30

Probability of absence

baseMap



Next steps....

- Development of prototype (version 0.1) web-based eradication tools software (October/November)
- Initial road test on active eradication program
 - Coati eradication on Robinson Crusoe Island
- Further road testing/workshops with potential users ??
- Development of eradication 'primer'
 - A handbook about decision support for eradication programs

